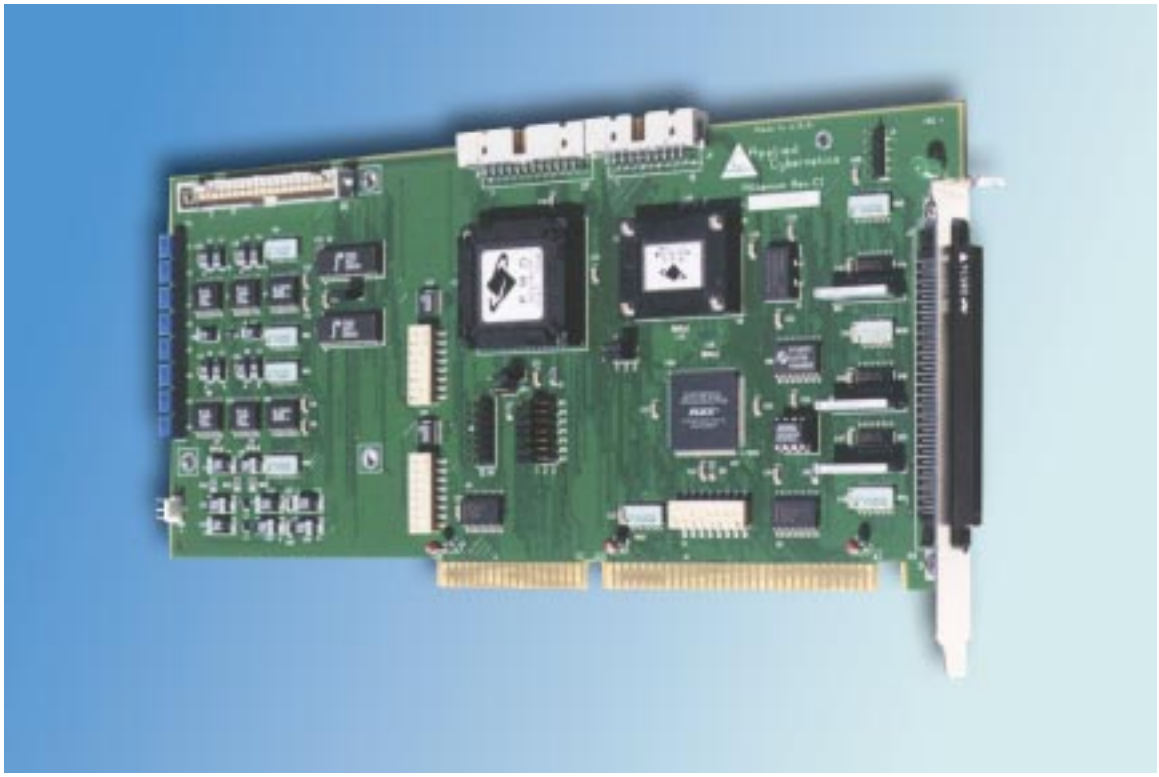
Cito
Systems

***ISA-bus Millennium* Series**
Motion Controller Board
For Brushless Servomotors

3m-0x-BL



Product Description

The Millennium brushless type multi-axis motion controllers model 3m-0x-BL implement the Navigator MC23xx series chipsets - dedicated motion processors from PMD. These controllers harness the power of the Navigator high-speed DSP chip and incorporate ASIC and surface mount technologies. They can install directly into a PC AT slot (ISA bus compatible) or can work standalone communicating via a serial link. The Millennium controllers are available in configurations of 1, 2 or 4 axes.

The DSP unit provides S-curve, trapezoidal, velocity contouring and electronic gearing profiling modes for Analog or PWM signal output. Onboard memory allows designers to capture on-the-fly motion data for analyzing system performance, tuning servo filters and diagnostic purposes. Motion trajectory segments can be blended into continuous motion path in the velocity mode.

The boards interface to external components via a 100 pin high density connector providing motor outputs and reading pulsed encoder (incremental or absolute), limit switches and home indicator input signals. They are capable of handling eight analog inputs and eight user-defined discrete I/Os.

The card is supported by C-Motion™ - extensive C-language software libraries and Windows drivers, which allow development of any motion control application. EasyMotion™, a Windows application package with the industry's first ever MotionWizard, assists in a quick and easy way to set up and tune even complex electro-mechanical systems.

The boards can be used in a variety of industries, such as robotic, machine tool, semiconductor, medical, food processing, textile and many others.

Features:

- Uses DSP and ASIC high speed dedicated motion processors in 1, 2 or 4 axes configuration
- Supports 2 or 3-phase brushless motors
- 6-step (Hall based) or sinusoidal commutation
- Independent or synchronous axes programming
- Open or closed servo loop operating modes
- Advanced PID filter with velocity and acceleration feedforward, bias offset and 32-bit position error
- Axis settled indicator and tracking window in addition to automatic motion error detection
- Choice of S-curve, trapezoidal, velocity contouring or electronic gearing motion profiles
- Asymmetric acceleration and deceleration to custom program a trapezoidal motion profile
- Velocity and acceleration changes on-the-fly for trapezoidal and velocity contouring profiles
- Position range from –2,147,483,648 to +2,147,483,647 counts
- Velocity range from -32,768 to +32,767 counts/sample with a resolution of 1/65,536 counts/sample in
- velocity contouring profile mode or from 0 to 32,767 counts/sample with a resolution of 1/65,536 counts/sample in all other modes
- Acceleration and deceleration range from –32,768 to 32,767 counts/sample^2 with a resolution of 1/65,536 counts/sample^2
- Jerk range from 0 to 1 counts/sample^3 with a resolution of 1/4,294,967,296 counts/sample^3
- Electronic gear ratio range from –32,768 to 32,767 (negative and positive direction)
- Programmable sample rate from 150 µsec to 3355 msec per axis
- Maximum incremental encoder rate up to 5.0 Mcounts/sec
- Maximum parallel feedback device rate up to 160.0 Mcounts/sec
- Parallel feedback device word size: 16 bits
- 3 Hall effect input signals per axis (TTL level)
- Commutation rate 10 kHz for 4 axes or 20 kHz for 1 and 2 axes
- +/-10V 16-bit DAC output signal
- PWM motor output signal of 10-bit resolution at 20 kHz (1 or 2 axes) or 10-bit resolution at 10 kHz (4 axes) – 50/50 PWM mode supports 2 or 3 phase motors, Sign/Magnitude PWM mode supports 2 phase motors only
- On-board 256 kByte memory buffer for data and parameters storage
- Parallel or serial communication interface
- Two-directional travel limit switches, home indicator and fault input per axis
- Automatic motor shutdown on motion error
- 8 general purpose 10-bit analog inputs in range of 0 to 5.0 V dc
- 8 general purpose discrete inputs and outputs expandable to 256 inputs and 128 outputs
- Programmable host interrupts
- Trace capabilities for system performance testing, servo-filter tuning and diagnostic purposes
- Software functions support coordinated linear and circular interpolation, point-to-point positioning and contouring, backlash compensation, jogging, homing, etc.
- Status reporting for position, speed and errors
- Infinite number of linear and arc segments for smooth motion
- Programmable event triggers for monitoring elapsed time, motion complete, position, motion error, limit switches and position wrap-around

Axes Control Signals Connector (J7)

Pin	Signal Name	Pin	Signal Name	Pin	Signal Name	Pin	Signal Name
01	QuadA1+	26	QuadA2+	51	QuadA3+	76	QuadA4+
02	QuadA1-	27	QuadA2-	52	QuadA3-	77	QuadA4-
03	QuadB1+	28	QuadB2+	53	QuadB3+	78	QuadB4+
04	QuadB1-	29	QuadB2-	54	QuadB3-	79	QuadB4-
05	Index1+	30	Index2+	55	Index3+	80	Index4+
06	Index1-	31	Index2-	56	Index3-	81	Index4-
07	Vcc (encoder)	32	Vcc (encoder)	57	Vcc (encoder)	82	Vcc (encoder)
08	GND (encoder)	33	GND (encoder)	58	GND (encoder)	83	GND (encoder)
09	Hall1A	34	Hall2A	59	Hall3A	84	Hall4A
10	Hall1B	35	Hall2B	60	Hall3B	85	Hall4B
11	Hall1C	36	Hall2C	61	Hall3C	86	Hall4C
12	GND (Hall)	37	GND (Hall)	62	GND (Hall)	87	GND (Hall)
13	PosLim1	38	PosLim2	63	PosLim3	88	PosLim4
14	NegLim1	39	NegLim2	64	NegLim3	89	NegLim4
15	Home1	40	Home2	65	Home3	90	Home4
16	AxisIn1	41	AxisIn2	66	AxisIn3	91	AxisIn4
17	AxisOut1	42	AxisOut2	67	AxisOut3	92	AxisOut4
18	PWMMagA1	43	PWMMagA2	68	PWMMagA3	93	PWMMagA4
19	PWMMagB1	44	PWMMagB2	69	PWMMagB3	94	PWMMagB4
20	PWMMagC1	45	PWMMagC2	70	PWMMagC3	95	PWMMagC4
21	Not used	46	Not used	71	Not used	99	Not used
22	DACA1	47	DACA2	72	DACA3	97	DACA4
23	DACB1	48	DACB2	73	DACB3	98	DACB4
24	GND (DAC)	49	GND (DAC)	74	GND (DAC)	99	GND (DAC)
25	N.C.	50	N.C.	75	N.C.	100	N.C.

User-defined Digital I/O Connector (J8)

Pin	Signal Name	Pin	Signal Name
01	PrlIn0	11	PrlIn5
02	PrlOut0	12	PrlOut5
03	PrlIn1	13	PrlIn6
04	PrlOut1	14	PrlOut6
05	PrlIn2	15	PrlIn7
06	PrlOut2	16	PrlOut7
07	PrlIn3	17	GND
08	PrlOut3	18	Vcc
09	PrlIn4	19	GND
10	PrlOut4	20	Vcc

Analog Input Connector (J9)

Pin	Signal Name	Pin	Signal Name
01	Analog1	14	AnalogRefLow
02	Analog2	15	AnalogGND
03	Analog3	16	AnalogGND
04	Analog4	17	AnalogVcc
05	Analog5	18	GND
06	Analog6	19	GND
07	Analog7	20	Vcc
08	Analog8	21	AxisOut1
09	AnalogIn1	22	AxisOut2
10	AnalogIn2	23	AxisOut3
11	AnalogIn3	24	AxisOut4
12	AnalogIn4	25	Watchdog
13	AnalogRefHigh	26	~HostIntrpt

Serial Channel Connector (J4)

Pin	Signal Name
01	SrlXmt
02	SrlRcv
03	Synch
04	GND
05	Vcc

12V Power Connector (J10)

Pin	Signal Name
01	+12V
02	GND
03	-12V

Environmental and Electrical Ratings

Dimensions	4.8” x 10.0”, 16-bit ISA Adapter
Storage Temperature	-40 °C to 125 °C
Operating Temperature	0 °C to 70 °C (an industrial version with an operating range of –40 °C to 85 °C is also available)
Power Consumption	1A @ 5V; 83mA @ +/-12V
Supply Voltage Limits	-0.3V to +7.0V
Supply Voltage Operating Range	4.75V to 5.25V
Analog Output Range	-10.0V to 10.0V
Analog Input Range	0.0V to 5.0V

Ordering information